

There is a second way to multiply two vectors.

the cross product. The cross product of two vectors, \vec{u} and \vec{v} , is denoted $\vec{u} \times \vec{v}$. There are many differences between the dot product and the cross product.

	Dot product	Cross product
Notation	$\vec{u} \cdot \vec{v}$	$\vec{u} \times \vec{v}$
Value	$\vec{u} \cdot \vec{v}$ is a scalar	$\vec{u} \times \vec{v}$ is a vector
Vanishes if	\vec{u} and \vec{v} are orthogonal	\vec{u} and \vec{v} are parallel
Works for	2D & 3D	3D only
Swaps & you get	$\vec{u} \cdot \vec{v} = \vec{v} \cdot \vec{u}$	$\vec{u} \times \vec{v} = -\vec{v} \times \vec{u}$

The cross product is somewhat a different beast. Let's go straight into the formula:

for $\vec{u}_1 = \langle x_1, y_1, z_1 \rangle$, $\vec{u}_2 = \langle x_2, y_2, z_2 \rangle$

$$\vec{u}_1 \times \vec{u}_2 = \langle y_1 z_2 - z_1 y_2, z_1 x_2 - x_1 z_2, x_1 y_2 - y_1 x_2 \rangle$$

The formula is really tricky to memorize.

There are two ways to memorize.

1. XYZZY method.

The x-component of $\vec{u}_1 \times \vec{u}_2$ is
 $y_1 z_2 - z_1 y_2$.

so **X** **yz** **zy** \rightarrow **xyzzy**.

The indices here are always **1 2 1 2**.

The other components can be guessed by shifting variables. Namely, you permute the variables x, y, z in a cyclic order, $x \rightarrow y$, and you get

the y -component, and the z -component.

$$\begin{array}{l} \text{X-component} = y_1 z_2 - z_1 y_2 \\ \downarrow \quad \quad \quad \downarrow \downarrow \quad \downarrow \downarrow \\ \text{Y-component} = z_1 x_2 - x_1 z_2 \\ \downarrow \quad \quad \quad \downarrow \downarrow \quad \downarrow \downarrow \\ \text{Z-component} = x_1 y_2 - y_1 x_2 \end{array}$$

2. Determinants (Makes sense only if you know matrices)

 Skip this if you've never seen matrices before.

This is just a suggestion on how to memorize, and will not be tested.

$$\vec{u}_1 = \langle x_1, y_1, z_1 \rangle = x_1 \vec{i} + y_1 \vec{j} + z_1 \vec{k}$$

$$\vec{u}_2 = \langle x_2, y_2, z_2 \rangle = x_2 \vec{i} + y_2 \vec{j} + z_2 \vec{k}, \text{ then}$$

$\vec{u}_1 \times \vec{u}_2$ is given by the determinant of the 3×3 matrix

$$\begin{pmatrix} \vec{i} & \vec{j} & \vec{k} \\ x_1 & y_1 & z_1 \\ x_2 & y_2 & z_2 \end{pmatrix}$$

The determinant of a matrix can be

computed as follows.

(A) Remove the first row, and consider 3 2×2

matrices formed by further removing each column:

$$\begin{array}{c} \vec{i} \quad \vec{j} \quad \vec{k} \\ \begin{vmatrix} x_1 & y_1 & z_1 \\ x_2 & y_2 & z_2 \end{vmatrix} \end{array} \rightsquigarrow \begin{array}{ccc} \begin{vmatrix} y_1 & z_1 \\ y_2 & z_2 \end{vmatrix} & \begin{vmatrix} x_1 & z_1 \\ x_2 & z_2 \end{vmatrix} & \begin{vmatrix} x_1 & y_1 \\ x_2 & y_2 \end{vmatrix} \end{array}$$

$$\rightsquigarrow \begin{array}{ccc} \begin{vmatrix} y_1 & z_1 \\ y_2 & z_2 \end{vmatrix} & \begin{vmatrix} x_1 & z_1 \\ x_2 & z_2 \end{vmatrix} & \begin{vmatrix} x_1 & y_1 \\ x_2 & y_2 \end{vmatrix} \end{array}$$

(B) Multiply each term with the corresponding entry in the first row:

$$\rightsquigarrow \begin{array}{ccc} \vec{i} \begin{vmatrix} y_1 & z_1 \\ y_2 & z_2 \end{vmatrix} & - \vec{j} \begin{vmatrix} x_1 & z_1 \\ x_2 & z_2 \end{vmatrix} & + \vec{k} \begin{vmatrix} x_1 & y_1 \\ x_2 & y_2 \end{vmatrix} \end{array}$$

(c) Add all of them, with alternating signs + - + ...

$$\leadsto +i \begin{vmatrix} y_1 & z_1 \\ y_2 & z_2 \end{vmatrix} - j \begin{vmatrix} x_1 & z_1 \\ x_2 & z_2 \end{vmatrix} + k \begin{vmatrix} x_1 & y_1 \\ x_2 & y_2 \end{vmatrix}$$

The determinant of a 2×2 matrix can be done via the same process.

(A) Remove the first row, and consider 2 1×1 matrices formed by further removing each column:

$$\begin{vmatrix} \cancel{y_1} & z_1 \\ y_2 & z_2 \end{vmatrix} \leadsto \begin{vmatrix} y_2 & z_2 \end{vmatrix} \quad \begin{vmatrix} y_2 & \cancel{z_2} \end{vmatrix}$$

(B) Multiply each term with the corresponding entry in the first row:

$$\leadsto y_1 \begin{vmatrix} y_2 & z_2 \end{vmatrix} \quad z_1 \begin{vmatrix} y_2 & \cancel{z_2} \end{vmatrix}$$

(c) Add all of them, with alternating signs + - + ...

$$\leadsto +y_1 z_2 - z_1 y_2$$

So we get

$$\vec{i} \times \vec{j} = (y_1 z_2 - z_1 y_2) \vec{i} - (x_1 z_2 - z_1 x_2) \vec{j} + (x_1 y_2 - y_1 x_2) \vec{k}$$

--- THE END ---

Example For $\vec{u} = \langle 1, 3, 4 \rangle$
 $\vec{v} = \langle 2, 7, -5 \rangle$
 (x = yz - zy!)

$$\vec{u} \times \vec{v} = \langle 3(-5) - 4(7), 4 \cdot 2 - 1 \cdot (-5), 1 \cdot 7 - 3 \cdot 2 \rangle$$

$$= \langle -43, 13, 1 \rangle.$$

The cross product has some weird properties!

0. Obviously $\vec{0} \times \vec{u}$ and $\vec{u} \times \vec{0}$ are both zero vector, $\vec{0}$.

1. $\vec{u} \times \vec{v} = -\vec{v} \times \vec{u}$.

2. $\vec{u} \times \vec{v} = \vec{0}$ if \vec{u} and \vec{v} are parallel.

Conversely, $\vec{u} \times \vec{v} = \vec{0}$ implies that \vec{u} and \vec{v} are parallel.

3. $\vec{u} \times \vec{v}$ as a vector is orthogonal to both \vec{u} and \vec{v} .

Namely, $\vec{u} \cdot (\vec{u} \times \vec{v}) = 0$ and $\vec{v} \cdot (\vec{u} \times \vec{v}) = 0$.

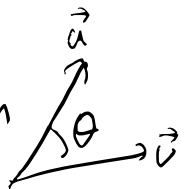
Example In the above example,

$$\vec{u} \cdot (\vec{u} \times \vec{v}) = 1 \cdot (-43) + 3 \cdot 13 + 4 \cdot 1 = -43 + 39 + 4 = 0$$

$$\vec{v} \cdot (\vec{u} \times \vec{v}) = 2 \cdot (-43) + 7 \cdot 13 + (-5) \cdot 1 = -86 + 91 - 5 = 0.$$

4. If \vec{u} and \vec{v} forms an angle of θ , then

$$|\vec{u} \times \vec{v}| = |\vec{u}| \cdot |\vec{v}| \sin \theta.$$



Remember that $|\vec{u} \cdot \vec{v}| = |\vec{u}| \cdot |\vec{v}| \cos \theta$.

In the case of dot product, $\vec{u} \cdot \vec{v} = 0$

if $\cos \theta = 0$, or if $\theta = \frac{\pi}{2}$ (90°),
namely when they're **orthogonal**.

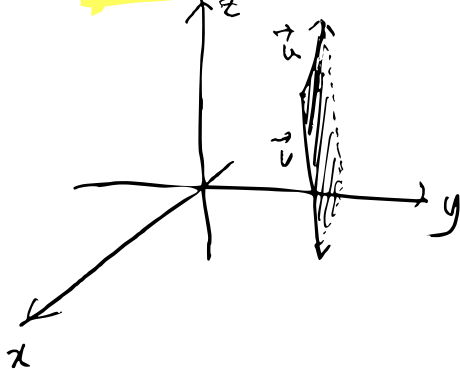
In the case of cross product, $\vec{u} \times \vec{v} = 0$

if $\sin \theta = 0$, or if $\theta = 0$ or π (0°),
namely when they're **parallel**.

5. From the above formula,

$|\vec{u} \times \vec{v}|$ is the area of the parallelogram formed by

\vec{u} and \vec{v} .



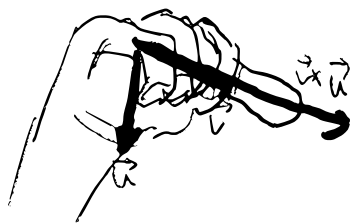
So, the area of the triangle
formed by \vec{u} and \vec{v} is
 $\frac{1}{2} |\vec{u} \times \vec{v}|$, being the half
of the area of the parallelogram.

6. The direction of $\vec{u} \times \vec{v}$ follows the **right hand rule**: among the two directions orthogonal to both \vec{u} and \vec{v} , it's the direction of the thumb as your fingers curl from \vec{u} to \vec{v} .



(Sorry about the picture)

This is another illustration of why $\vec{u} \times \vec{v} = -\vec{v} \times \vec{u}$.



(Sorry about the picture)

Example $\vec{i} \times \vec{j}$ has length $|\vec{i}| \cdot |\vec{j}| \cdot \sin \frac{\pi}{2} = 1$,

and has the direction the same as the positive z -direction,

so $\vec{k} = \vec{i} \times \vec{j}$. Indeed $\langle 1, 0, 0 \rangle \times \langle 0, 1, 0 \rangle$

$$= \langle 0 \cdot 0 - 0 \cdot 1, 0 \cdot 0 - 1 \cdot 0, 1 \cdot 1 - 0 \cdot 0 \rangle = \langle 0, 0, 1 \rangle.$$

Warning It is extremely important to not mix up vectors with scalars.

For example, you can't add a scalar to a vector. Also, you can't divide by vectors.

Exercise Suppose $\vec{u}, \vec{v}, \vec{w}$ are vectors, and a, b are scalars. Check if the following expressions are valid and explain why.

1. $a(\vec{u} \times \vec{v}) \times \vec{w}$

2. $(\vec{u} + |\vec{v}|) \cdot b\vec{w}$

3. $(a+b)a\vec{u} + \vec{v} \cdot \vec{w}$

4. $\frac{|\vec{v}|}{\vec{w}}(\vec{u} \cdot \vec{v})$

5. $\frac{(\vec{u} \cdot \vec{v})^2}{a|\vec{w}|} \vec{u} + b(\vec{v} \times \vec{w}) \times \vec{u}$

A fun fact is that, just as the cross product computes the area of a parallelogram, the cross product and the dot product combined can compute the volume of a parallelepiped (3D version of parallelogram).

$|\vec{u} \cdot (\vec{v} \times \vec{w})|$ computes the parallelepiped formed by

the three vectors $\vec{u}, \vec{v}, \vec{w}$.

